



SETUPMENU (Menu LED permanent on)



		Status LED:									
		off	purple	red	blue						
A	operating mode			tail gyro	flybarless						
B	position of installation			upright	flat						
C	swashplate - servo frequency	50 Hz	65 Hz	120 Hz	200 Hz						
D	tailservo - neutral impulse		960 µS	760 µS	1520 µS						
E	tailservo - frequency	50 Hz	165 Hz	270 Hz	333 Hz						
F	tailservo - limit	<i>tail stick input - limit left / limit right</i>									
G	tailsensor direction			normal	inverse						
H	swashplate - servo sub trim	middle position	CH1 trim	CH2 trim	CH3 trim						
I	swashplate mixing	mechanically		90°	120°	140°					
I	servo reversing (number of flashes)			1	2	3	4	1	2	3	4
J	regulation adjustment	<i>by aileron stick input adjust 6° of cyclic pitch</i>									
K	collective pitch setup	<i>move the pitch stick to max. and min. and adjust pitch by tail stick input in each case</i>									
L	swashplate - limit	<i>move aileron, elevator and pitch and adjust the cyclic range by tail stick input</i>									
M	swashplate - sensor direction	nor.	nor.	inv.	inv.	inv.	nor.	nor.	inv.		
N	pirouette optimization			normal				inverse			

PARAMETERS MENU (Menu LED flashing)



		Status LED:							
		off	purple	red (flashing)	red	blue (flashing)	blue		
A	swashplate fine trimming	<i>aileron + elevator stick input</i>			<i>discard changes by tail stick input</i>				
B	control behaviour	PC	normal	sport *	pro	extreme	radio		
C	swashplate - pitching up behaviour	PC	very low	low	medium *	high	very high		
D	tail - heading Lock-Gain	PC	very low	low	medium *	high	very high		